Message reliability and caching for publish/subscribe systems

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Publish/subscribe

Message completeness

Temporal logic

Safety and Liveness

Axioms for p/s systems

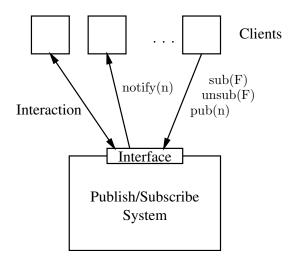
Distributed Implementaion

Rebeca

Publish/Subscribe

- Enables loosely coupled communication using notifications.
- Two kinds of "clients"
 - Producers publish notifications
 - Consumers subscribe to notifications
- Notification service
 - Decouples producers from consumers
 - Delivers a published notification to all consumers with a matching subscription

Interface

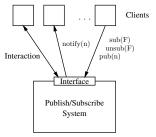


Basic Definitions and Assumptions

- ► A filter F is a mapping from the set of notifications N to the boolean values *true* and *false*.
- A notification *n* matches a filter *F* iff F(n) = true.
- ► Set of notifications matched by a filter F and by a set of filters A is denoted by N(F) and N(A), respectively.
- Notifications are unique and can be published only once.

Black box view of a publish/subscribe system

 Describes the system behavior by solely looking at its interface.



Interface Operations (set of all actions A)

sub(Y, F)	Client Y subscribes to filter F
unsub(Y, F)	Client Y unsubscribes to filter F
ack(Y,F)	System notifies client Y about
	message completeness guarantee
notify(Y, n)	System notifies client Y notified about n
pub(X, n)	Client X publishes n

Multicast

- publish/subscribe is special type of multicast
 - event-based
 - dynamically created groups
- problems classically considered for multicast:
 - message completeness
 - message order
 - etc.

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- better: after a client subscribes to a filter, there is a future time at which he is guaranteed to see all messages published thereafter
- even better: after a client subscribes to a filter, there is a future time the client is notified about at which he gets message completeness guarantee

The Need for a formal treatment

- A formal specification
 - defines precisely what is expected from a correct system and
 - allows to reason about the correctness of an implementation.
- A formal treatment gives new insights that could otherwise be overlooked!
- Linear Temporal Logic offers a formalizm suitable for characterization of the behaviour of distributed systems

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predicate applied to trace σ refers to first state s₀ or first operation op₁

Temporal quantifiers

For some formula ϕ and $\sigma = s_0, op_1, op_2, \ldots, op_n$,

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LTL and Concurrency

- ► LTL is well-suited to describe concurrent systems
- A concurrent system is replaced by a nondeterministic sequential one.
- The concurrent execution of two operations in the real system is replaced in the model by the nondeterminism of which one occurs first.
- ► This type of nondeterminism is conceptually different from that studied in the area of automata theory (⇒ branching time).

LTL Examples

- ► ♢□A
- ► □◊A
- $A \Rightarrow \Diamond B$
- $\blacktriangleright \ \Box[A \Rightarrow \Diamond B]$
- $\blacktriangleright \ \Box[A \Rightarrow \Box A]$
- $\blacktriangleright \Box [\Box A \Rightarrow \Diamond \Box B]$
- $\blacktriangleright \Box [A \lor \Box \neg A]$

State Variables in p/s systems

P_X	set of published notifications
S_Y^{ack}	set of acknowledged subscriptions
S_Y^{pend}	set of pending subscriptions
D _Y	multiset of delivered notifications

Initial values of state variables: \emptyset for all of them

Effect of interface operations on state variables

pub(X, n)	$P'_X = P_X \cup \{n\}$
sub(Y, F)	$S_{Y}^{pend'} = S_{Y}^{pend} \cup \{F\}$
unsub(Y, F)	$S_Y^{ack'} = S_Y^{ack} \setminus \{F\}; \ S_Y^{pend'} = S_Y^{pend} \setminus \{F\}$
ack(Y.F)	$S_Y^{pend'} = S_Y^{pend'} \setminus \{F\}; \ S_Y^{ack'} = S_Y^{ack} \cup \{F\}$
notify(Y, n)	$D'_{Y} = D_{Y} \cup \{n\}$

Safety and Liveness

Safety Conditions

- Something "irremediably" bad will never happen.
- Usually, phrased as an invariant of the system.
- Usually, trivially satisfied by doing nothing.
- General form: $Init \Rightarrow \Box \neg A$.
- Violation can be detected after *finite* time.
- E.g. partial correctness (Program never halts with wrong result)

Safety and Liveness (2)

Liveness Conditions

- Something "good" that should happen eventually happens.
- Usually, trivially satisfied by doing *everything*.
- General form: $Init \Rightarrow \Box[A \Rightarrow \Diamond B]$.
- Violation can be detected after *infinite* time only.
- Example: Termination (Program eventually halts)
- Many useful system properties (e.g., total correctness) can be expressed as the intersection of safety and liveness conditions.

Safaty axioms

A publish/subscribe system satisfies message complete safety if

$$\Box \Big[\textit{notify}(Y, n, X) \Rightarrow \big[\bigcirc \Box \neg \textit{notify}(Y, n, X) \big]$$
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$$\Box \Big[\textit{notify}(Y, n, X) \Rightarrow \exists F \in S_Y^{\textit{pend}} \cup S_Y^{\textit{ack}}. n \in N(F) \Big]$$
(4)

Liveness axioms

A publish/subscribe system satisfies message complete liveness if

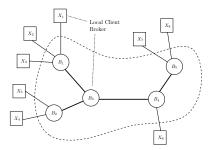
$$\Box \Big[(sub(Y,F) \land \neg \Diamond unsub(Y,F)) \Rightarrow \Diamond [ack(Y,F)]$$
 (5)

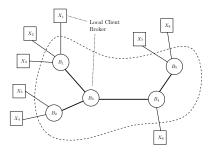
Liveness axioms

A publish/subscribe system satisfies message complete liveness if $\Box \left| (sub(Y,F) \land \neg \Diamond unsub(Y,F)) \Rightarrow \Diamond [ack(Y,F)] \right|$ (5)► $\Box | (ack(Y, F) \land \neg \Diamond unsub(Y, F)) \Rightarrow$ $(\Diamond pub(X, n) \land n \in N(F) \Rightarrow$ $\langle \text{notify}(Y, n, X) \rangle$ (6)

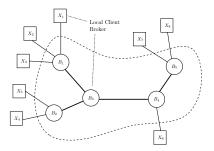
Correctness

A publish/subscribe system is *correct*, if it satisfies safety and liveness.

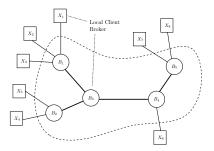




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- Each broker B manages a mutually exclusive set of local clients L_B and only communicates directly with its neighbor brokers N_B.

Assumptions

- Broker topology assumed to be acyclic.
- Channels are reliable (no corrupted, duplicated, lost, or spurious messages).
- Message latency is bounded.
- Communication with clients conceptually treated as message passing but assumed to be instantaneous.

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- Processing of *forward* and *pub* messages hardwired.
- Processing of admin messages is customized by implementing an instance of the administer procedure.

If a broker receives a forward(n) / pub(n) message from a neighbor / local client, it sends a forward(n) / notify(n) message to all neighbors / local clients D for which there is a routing entry (F, D) with n ∈ N(F).

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- But a notification is never passed back to the neighbor it was received from.
- ► As the topology is acyclic, duplicate notifications are avoided.
- As every notify(Y, n) has a preceding pub(X, n), no spurious notifications are delivered.

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 - Routing with filter merging

Rebeca

- started by Ludger Fiege and Gero Mühl, TU Darmstadt as Java-based implementation of p/s system
- implemented along the lines of formal framework
- based on microkernel architecture with routing component as kernel
- ▶ ported to C# by Andreas Ulbrich
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- Rebeca promises to become the first ever publish/subscribe system whose correctness can be formally proven!

Future Work

- Routing in cyclic topologies
- Funnel functions
- Fault tolerance
- Adaptivity
- Integration of routing and composite event detection
- Streaming operators
- Quality of Service

Thank You.

Questions?

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